

Application of Lock-in Thermography for Defect Localisation at Opened and Fully Packaged Single- and Multi-chip Devices



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Werkstoffmechanik

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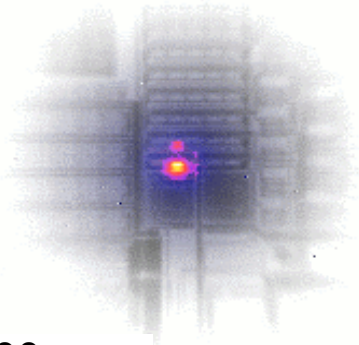
Fraunhofer Institute for Mechanics of Materials



Otwin Breitenstein

Max Planck Institute of Microstructure Physics

Overview



100 μm

- **The principle of Lock-in Thermography**
- **Defect localisation at open devices**
- **High resolution imaging**
- **Defect localisation at fully packaged devices**
- **Conclusion / Discussion**

Infrared imaging

Detector wavelengths ranges

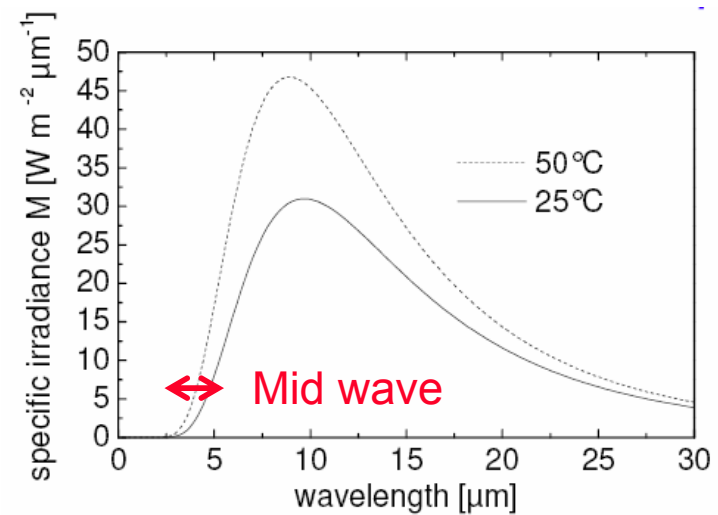
- 1-2 μm (short wave)
- 3 -5 μm (mid wave),
- 8-10 μm (long wave),

Optimal wavelength range for IR imaging near room temperature: Mid Wave

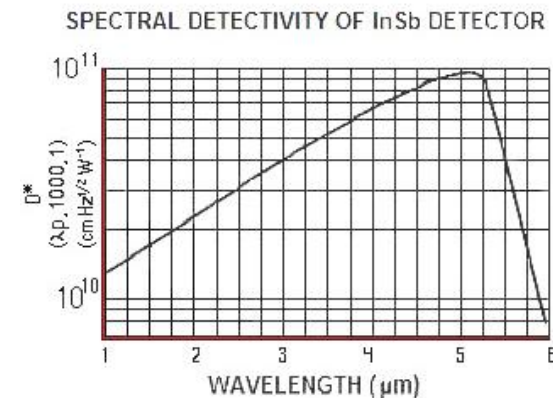
Detector types for MW:

focal plane arrays made from:

- cadmium mercury telluride (CMT)
- platinum silicide (PtSi)
- Indium antimonide (InSb)



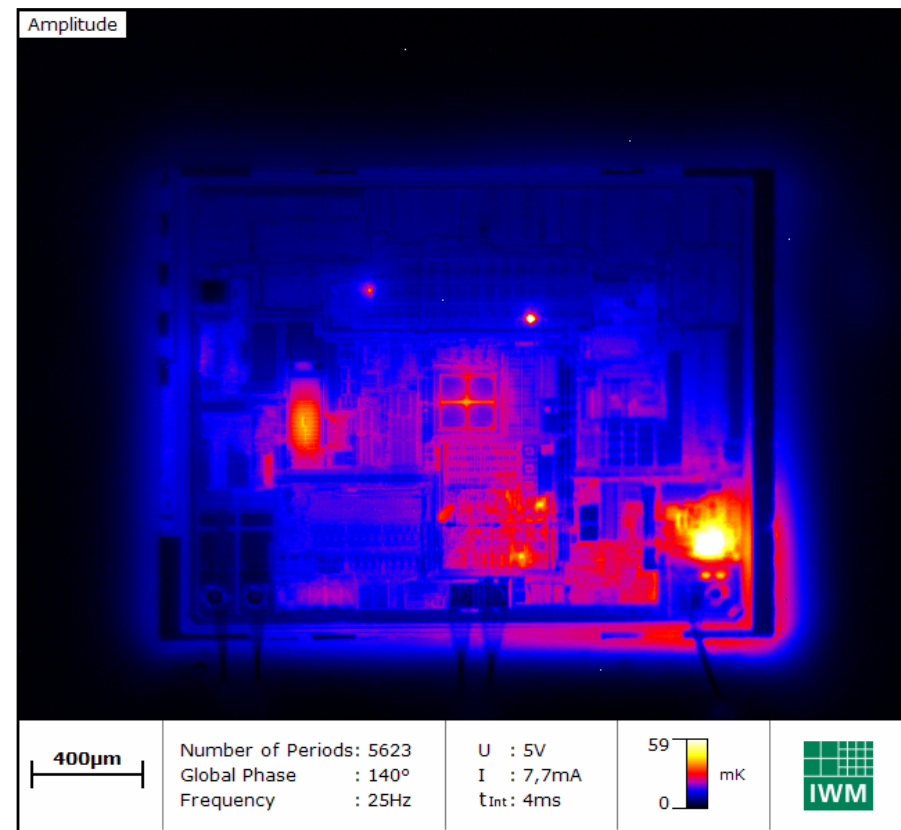
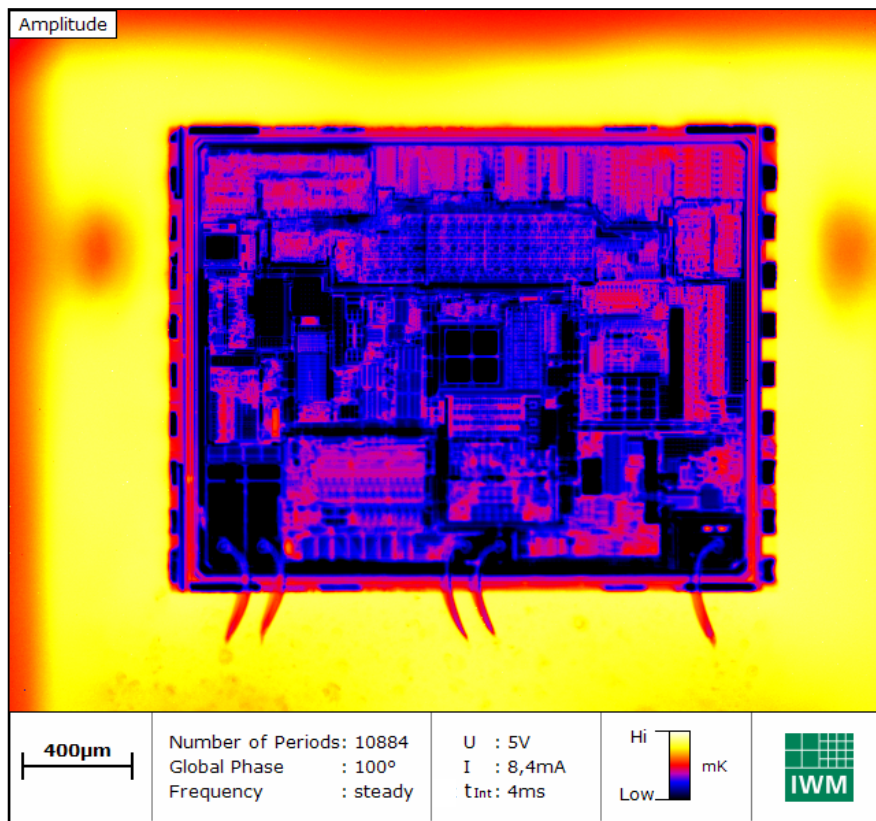
Spectral distribution of a black body



Spectral sensitivity

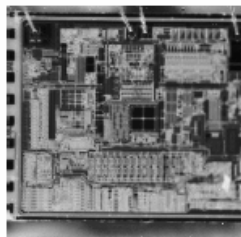
The principle of Lock-in Thermography (LIT)

What is the main difference between steady-state and Lock-in Thermography?

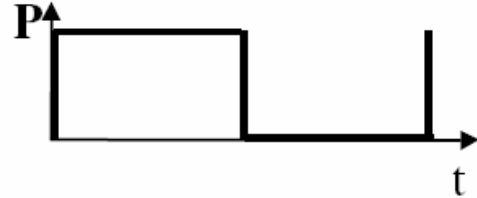


**Two-phase
image
processing
procedure:**

Single incoming
frames
(incl. topography
and noise)



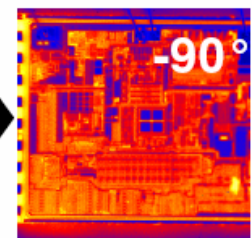
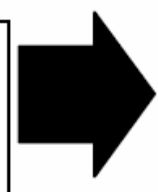
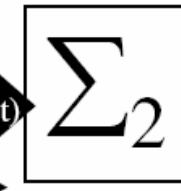
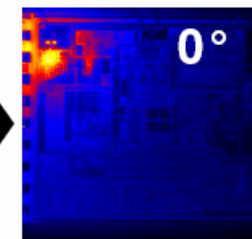
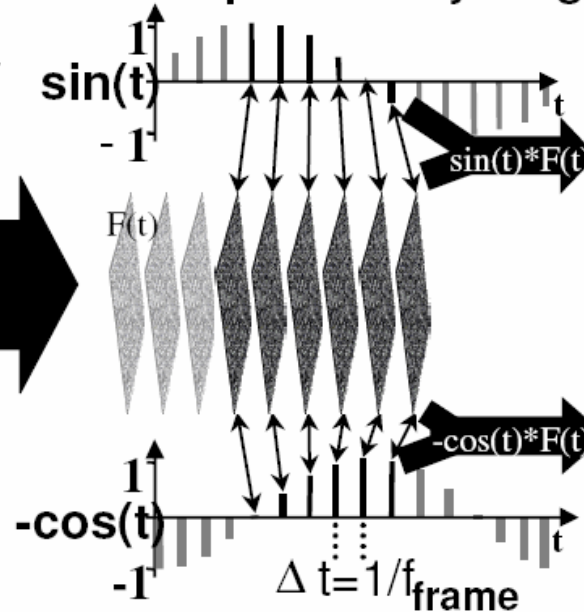
Heating power



**Averaging in 2 separate
frame storages !**



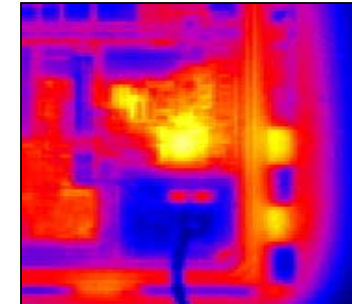
Multiplication by weighting factors



- both resulting signals are influenced by emissivity → base for calculating Amplitude and Phase

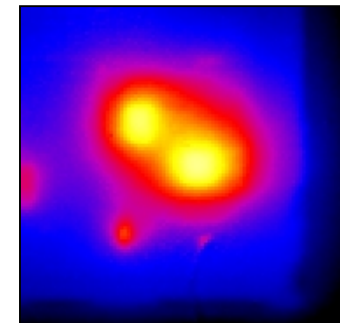
Amplitude:

$$A = \sqrt{\left(S^{0^\circ}\right)^2 + \left(S^{-90^\circ}\right)^2}$$



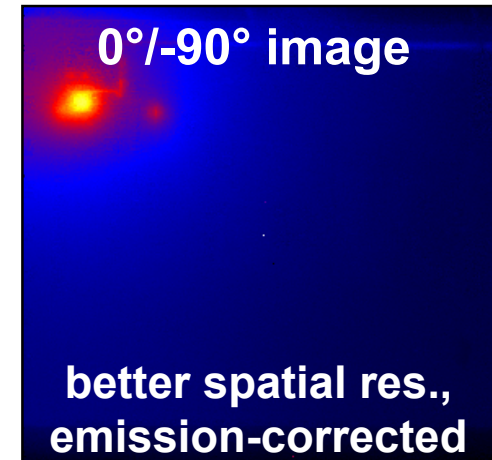
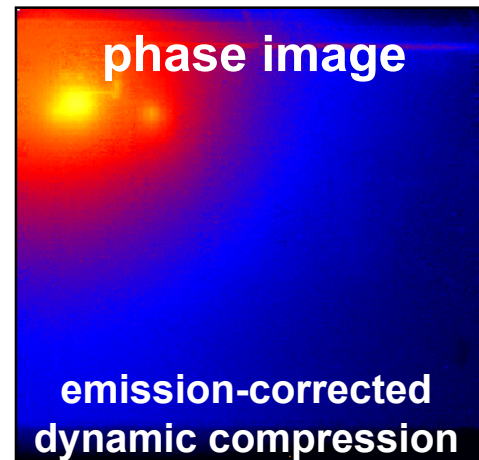
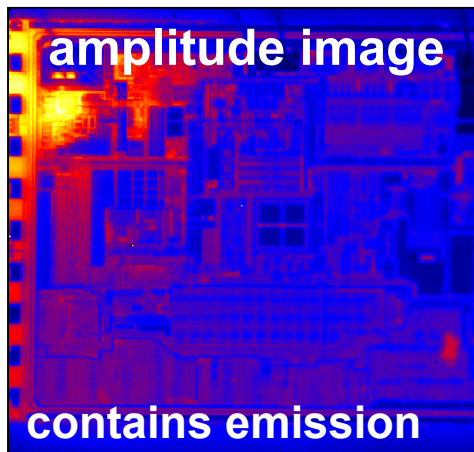
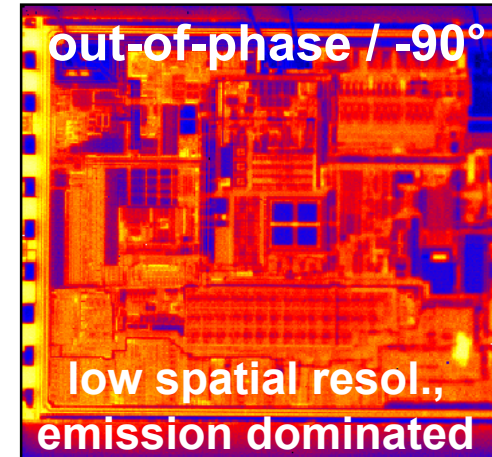
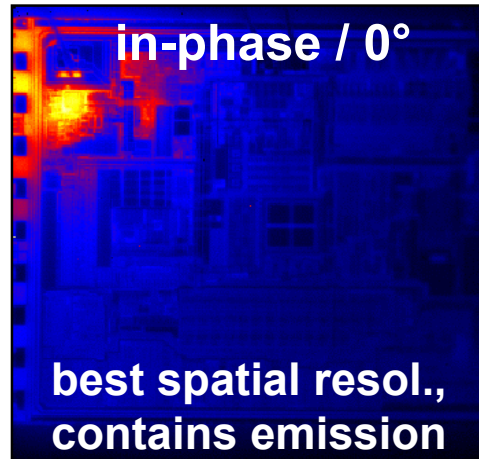
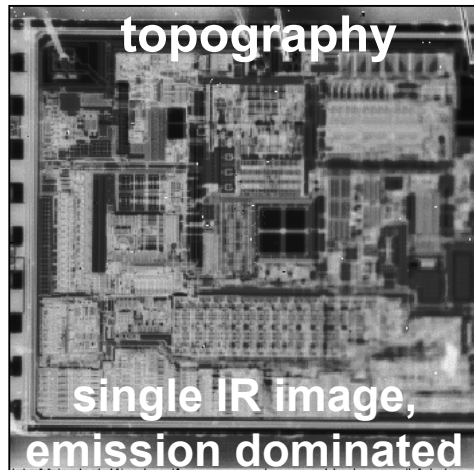
Phase:

$$\Phi = \arctan\left(\frac{-S^{-90^\circ}}{S^{0^\circ}}\right)$$



Advantages phase:

- no emissivity contrast
- “dynamic compression” in the phase image allows detection of weak hot spots even in the closer area to strong hot spots
- determining the phase shift allows a defect depth localization

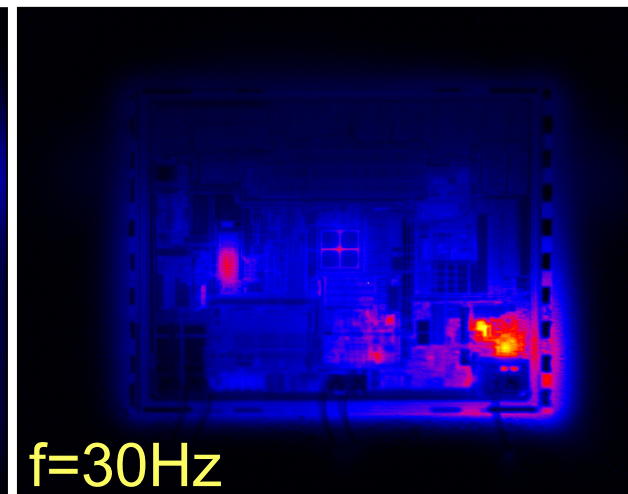
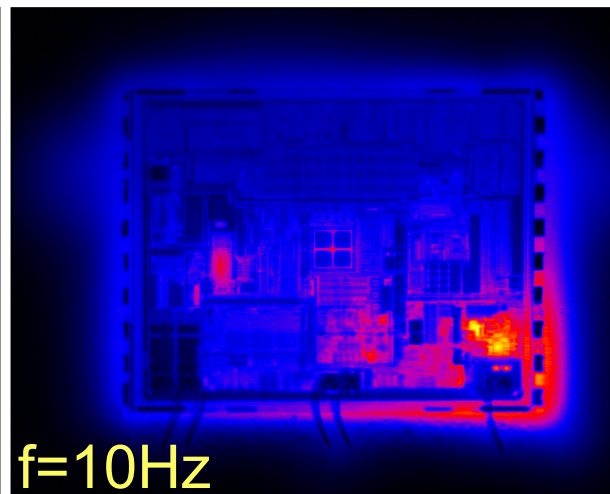
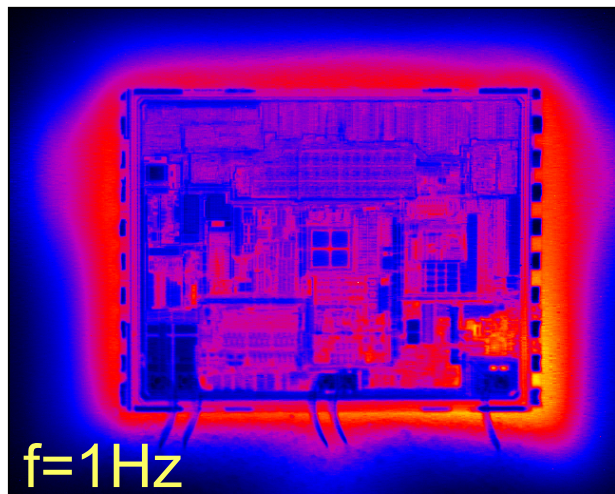


Important factor of influence: the lock-in frequency $f_{Lock-In}$

- taking into account calculating the **thermal diffusion length**:

$$\Lambda \sim \frac{1}{\sqrt{f_{Lock-In}}}$$

→ Spatial resolution increases the higher the lock-in frequency is

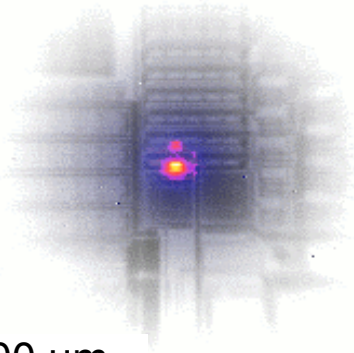


LiT- system used for measurements:

- „Thermosensorik“ InSb 640XL
- InSb – detector (spectral range: $1.5\mu\text{m} - 5\mu\text{m}$)
- 640x512 pixel, $15\mu\text{m}$ pixel pitch
→ high spatial resolution
- sample excitation voltage: 0 – 50V
- framerate: 100Hz (fullframe) up to 380Hz (subframes)



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100 μm

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- Conclusion / Discussion

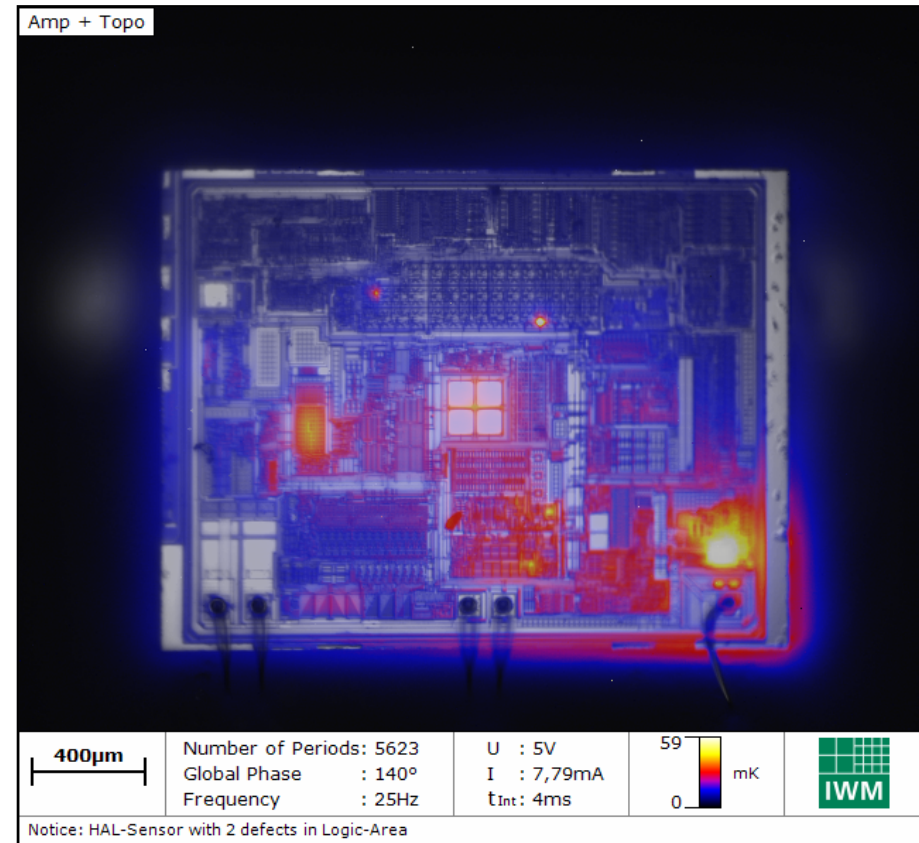
Standard: defect localisation at open devices

Localisation of thermal active defects:

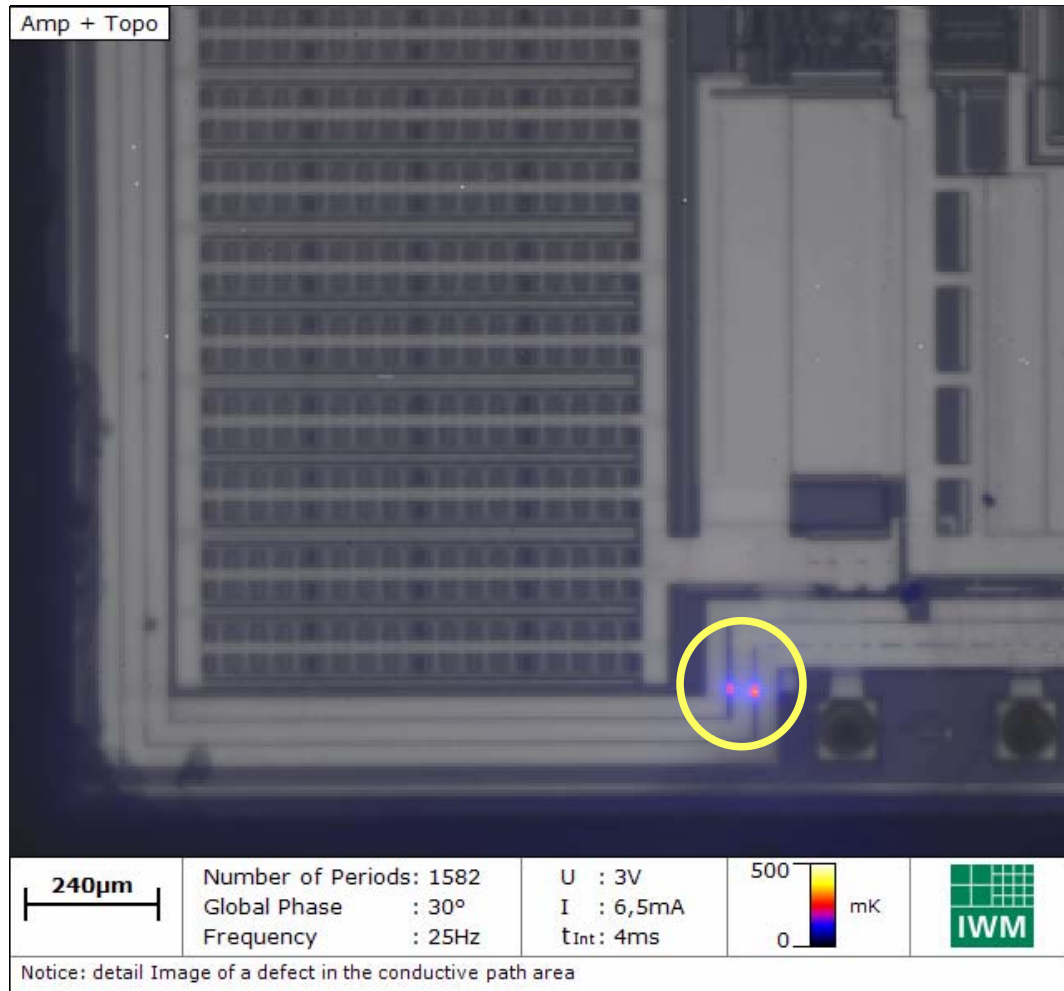
- line shorts
 - oxide breakdowns
 - transistor / diode defects
 - latch-ups, ESD defects
-
- IC is opened for optical access via removing the mould compound using e.g. chemical etching

Challenge:

- root causes of defects can be influenced → e.g. metal splinter can be removed by chemical etching

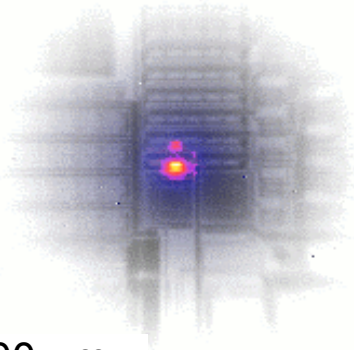


Example I: failed device with short path



- temperature-resolution: **<100 μK**
- power dissipation detection limit : **several μW**
- **sensitivity about 3 orders better than for steady state mode!**
- lateral resolution: about **5 μm**

Overview



100 μm

- The principle of Lock-in Thermography

Defect localisation at open devices

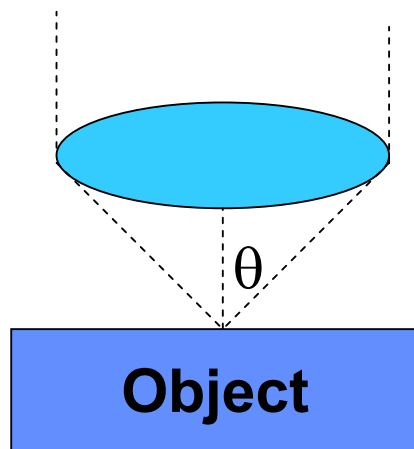
High resolution imaging

Defect localisation at fully packaged devices

- Conclusion / Discussion

High resolution IR imaging

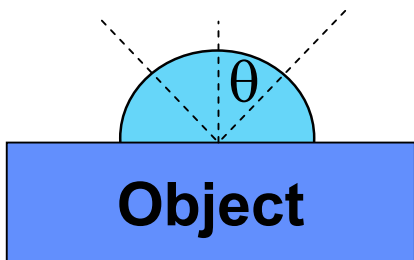
- **Aim:** Improving the optical resolution for a more accurate localisation of defects
- **Problem:** wavelength used: $5\mu\text{m}$, diffraction limits the resolution
- **Solution:** Increasing n by using different materials above object



$$\Delta x = \frac{0.5 \lambda}{NA}$$

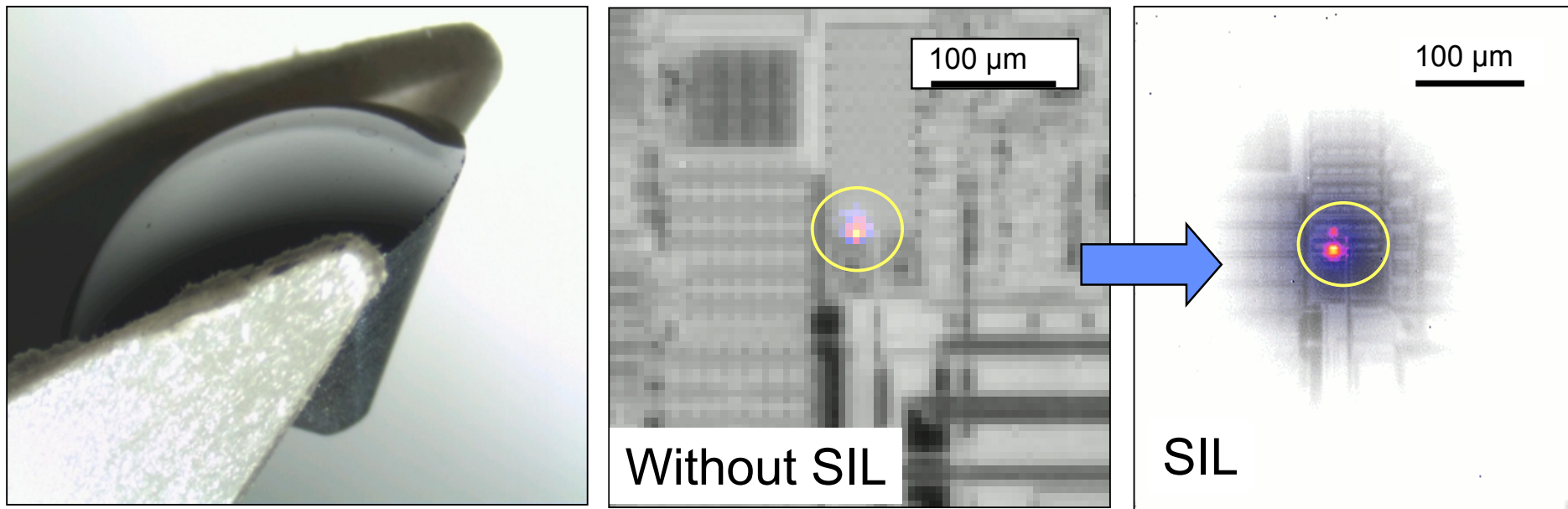
$$NA = n \cdot \sin \theta$$

NA...Numeric Aperture
n...index of refraction



Material	Index of refraction n
Quartz	1.544
Diamond	2.417
Silicon (IR)	3.43
Germanium	4.02

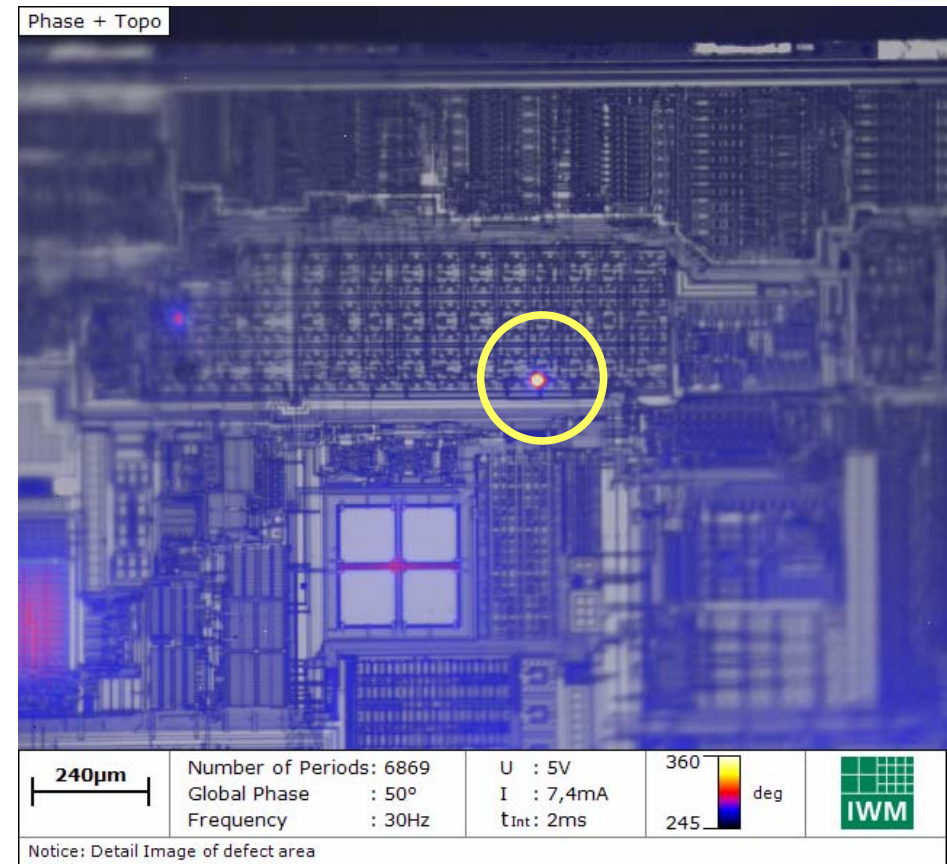
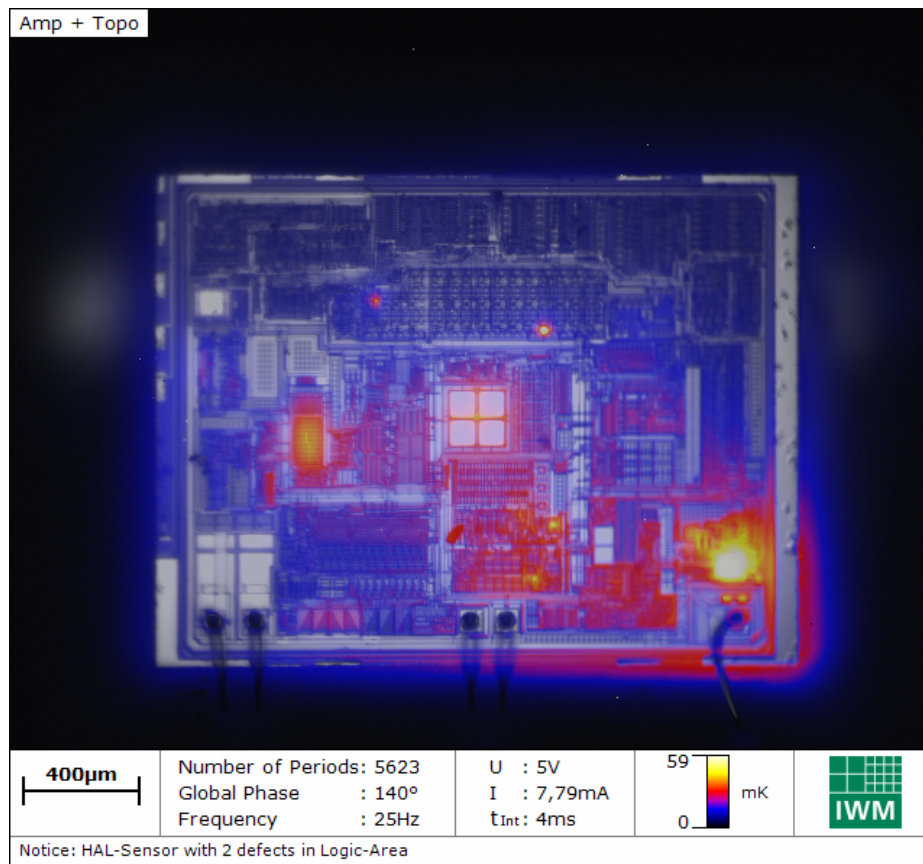
Results using hemispheric SIL made of Silicon



Left: Silicon - SIL in a tweezers: Dimension is around 3mm

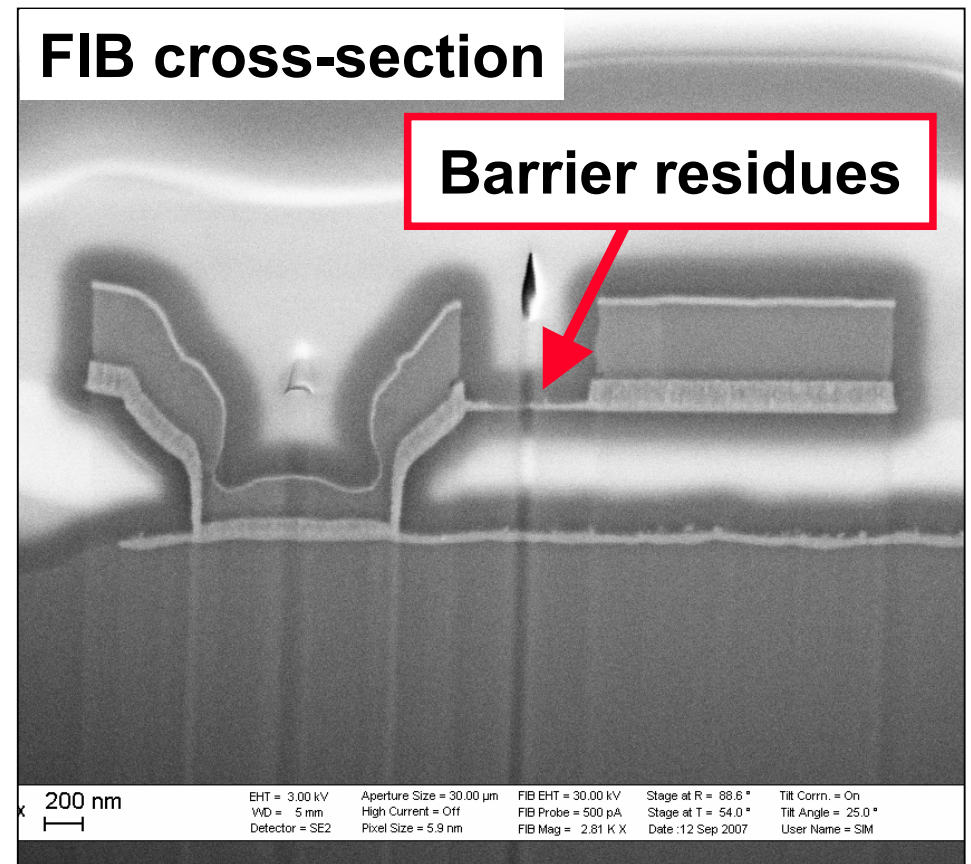
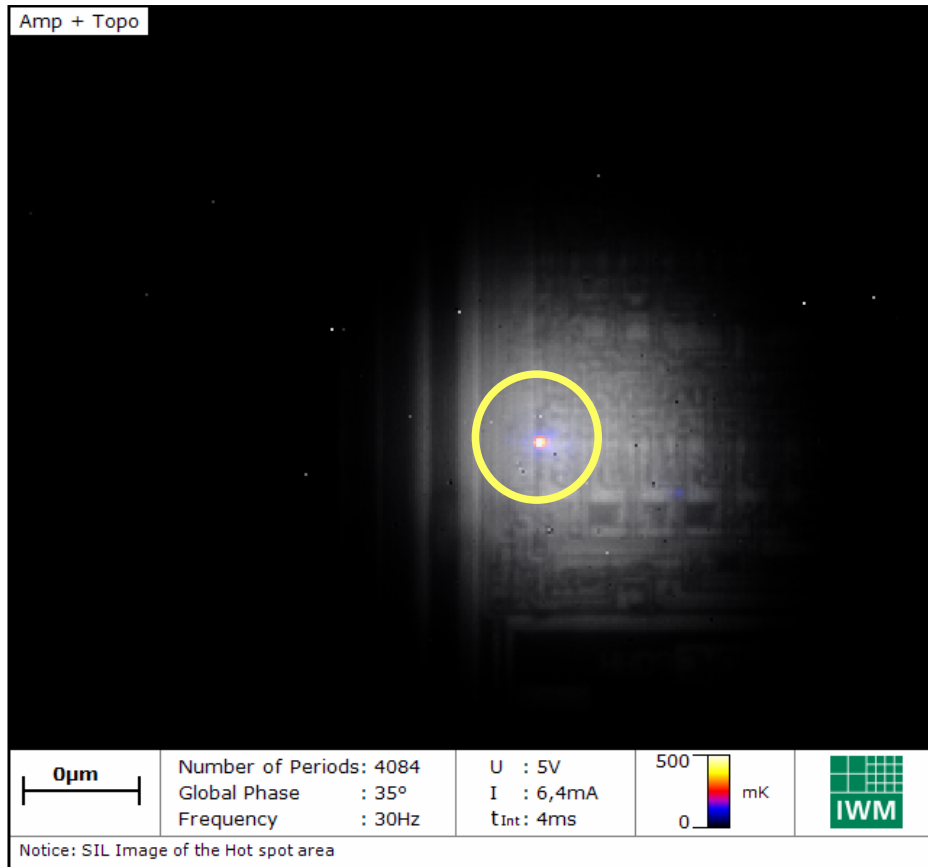
Right: SIL in application detecting a heat spot with high spatial resolution

Example II: Lock-in thermography for defect localisation with following cross-section

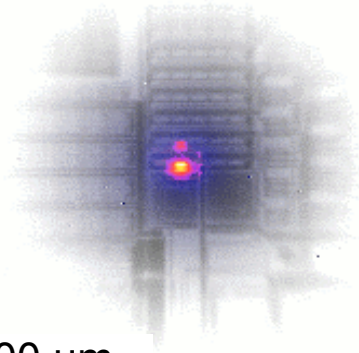


Application of SIL imaging for better spatial resolution → smaller cross-section area

Example II: Lock-in Thermography for defect localisation with following cross-section



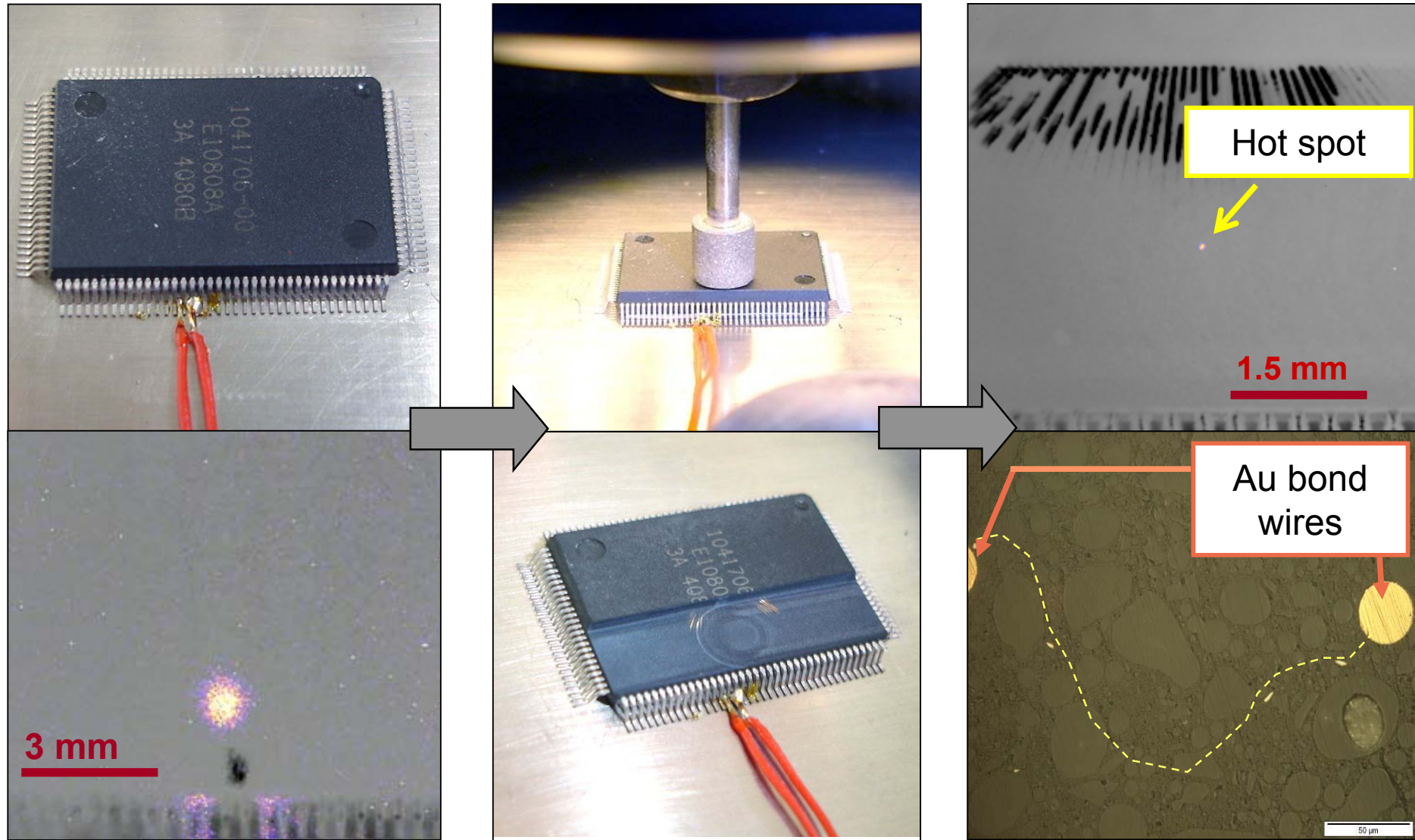
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Example III: Short localization at a fully packaged single chip device



Example IV: Defect localization at a stacked die device

- first LIT- measurement was done at fully package stacked die

Result:

hot spot was obtained in the chip area

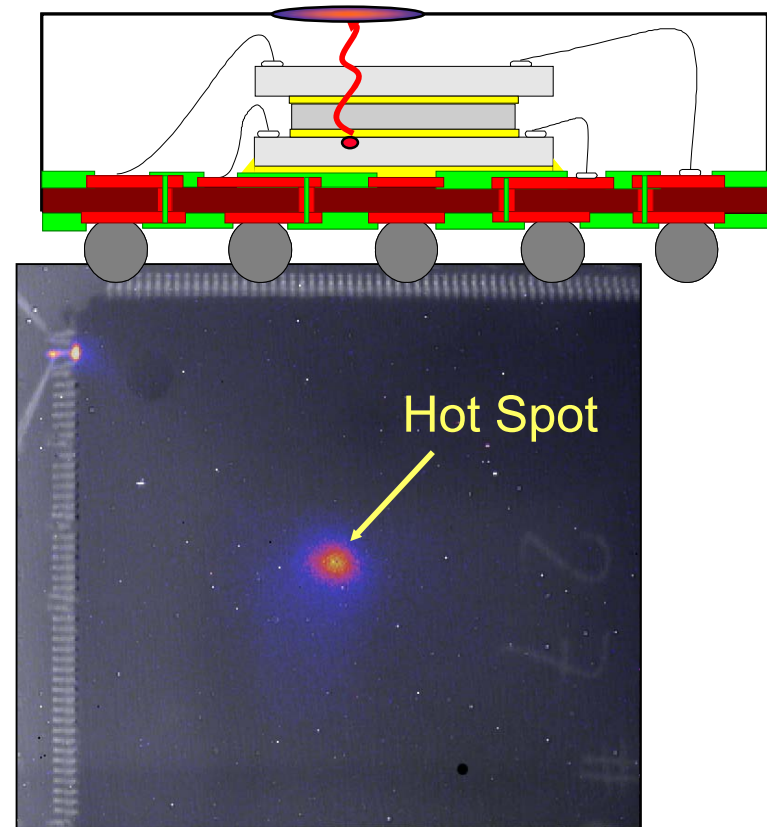
Challenge:

poor spatial resolution, unknown defect depth

Next step:

device opening, removal of Mold compound above the upper chip by chemical etching

→ additional LIT measurement



Thermogramm of the fully packaged device
(Amplitude-picture overlaid with topography)

Example IV: Defect localization at a stacked die device

- second LIT-measurement

Result:

hot spot was obtained in the chip area again,
spatial resolution was significantly increased

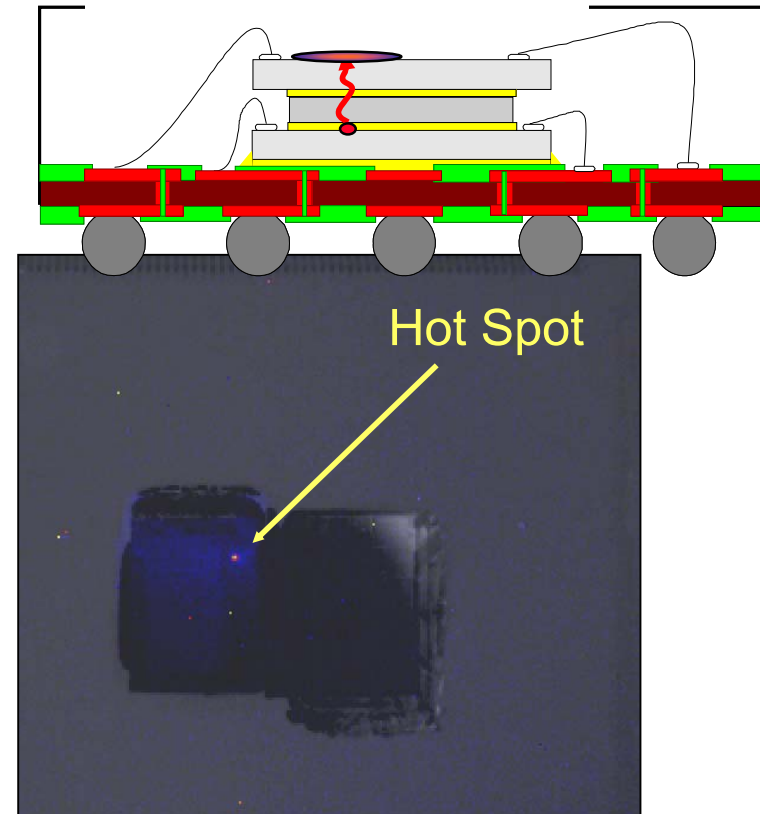
Challenge: silicon is IR-transparent

→defect depth is still unknown

Next step:

→ disconnection of the upper chip
layer via removing the bondwires

→ Third electrical / LIT-measurement



Thermogramm after opening the device
(Amplitude-picture overlaid with topography)

Example IV: Defect localization at a stacked die device

- third LIT – measurement

Result:

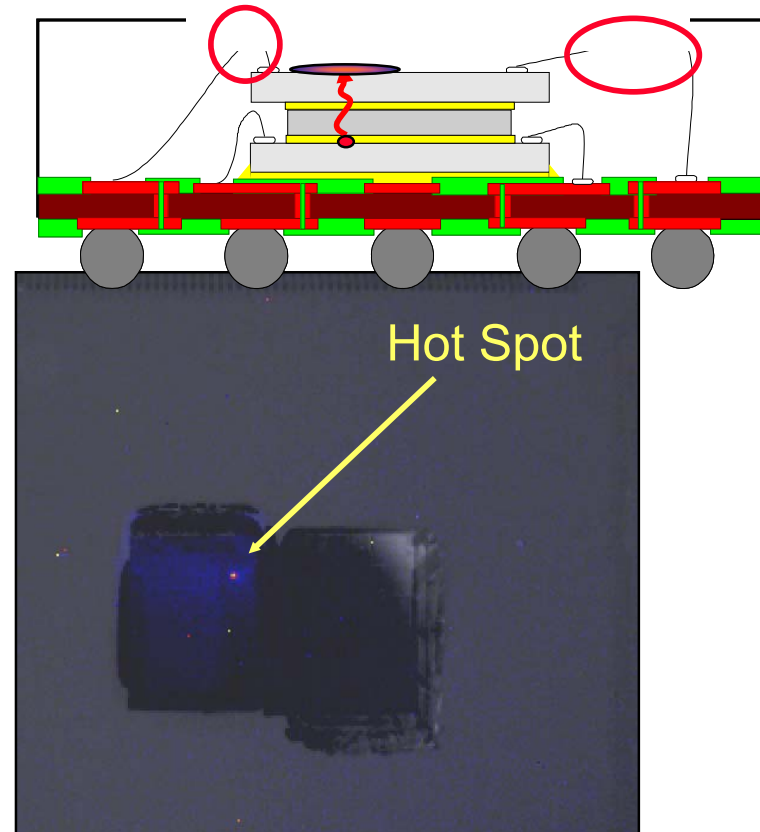
similar to second LIT, Short defect at the lower chip due to the fact that upper chip layer is inactive

Challenge:

procedure is time-consuming

→ defect localization using the **phase information** of the LIT-measurement

→ **only one measurement necessary to detect defect**



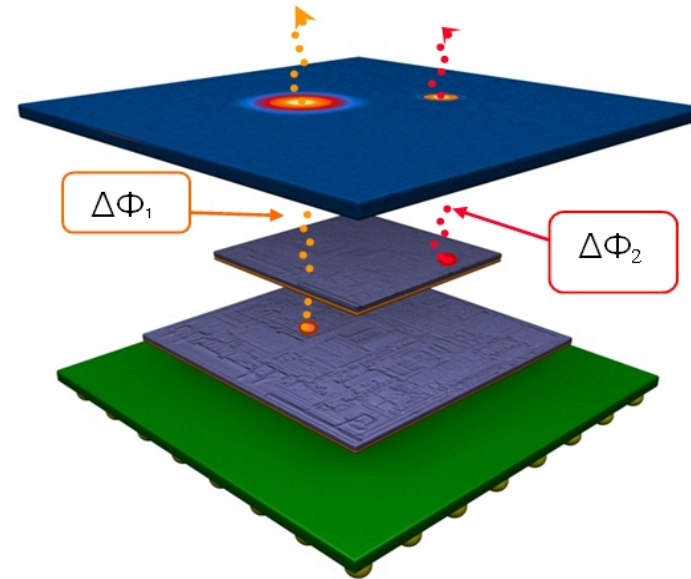
Thermogramm after disconnecting the upper chip layer
(Amplitude picture overlaid with topography)

Aim:

non-destructive defect localization at fully packaged complex devices

Solution: “Heat flow takes time”

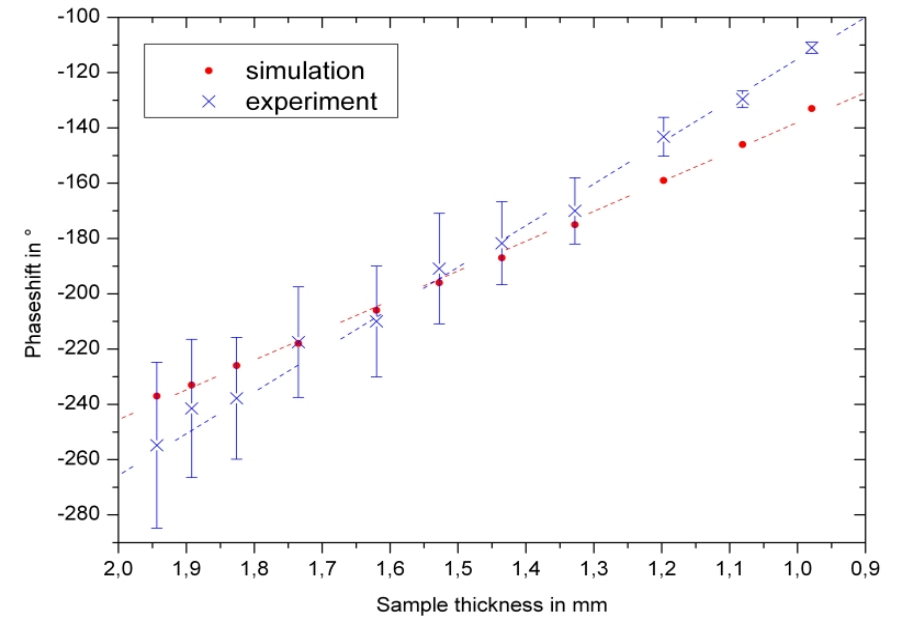
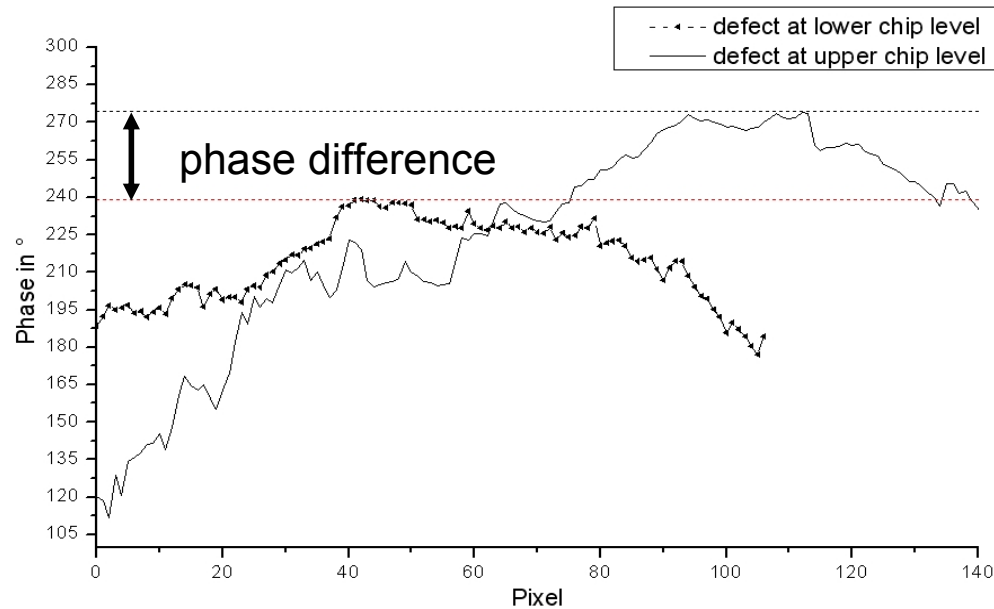
→ phase information give the opportunity determining the defect depth



Challenge:

→ heat occurring from the defect has to pass the mould compound before it can be observed by IR-detector → thermal spreading reduces spatial resolution

3D defect localisation using the phase information (Pidea Full Control)

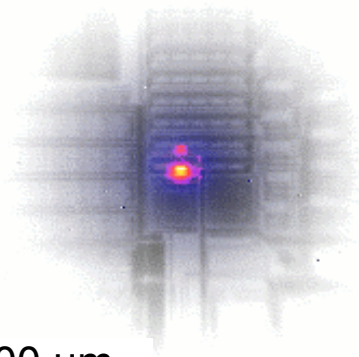


former experiments at **stacked die devices** investigated the relationship between phase shift and defect depth (**ESTC 2008, ISTFA 2008**)

phase difference is base calculating a depth difference: $34^\circ \rightarrow 237\mu\text{m}$

real difference: $195\mu\text{m} \rightarrow$ **3D localisation is possible** (Part of research)

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Conclusion:

Lock-in Thermography:

- is a powerful method for failure localisation
- Easy sample preparation and works from the front or back side of the chip
- generally works at any temperatures (range is depending to the detector material)
- is more sensitive in comparison to steady state methods ($<100\mu\text{K}$, μW range)
- Satisfying spatial resolution for failure localisation on microelectrical devices:
5 μm (standard optics), 1.2 μm (SIL)
- is also usable for non-destructive failure localization in packaged devices

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Thank you for your attention!



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